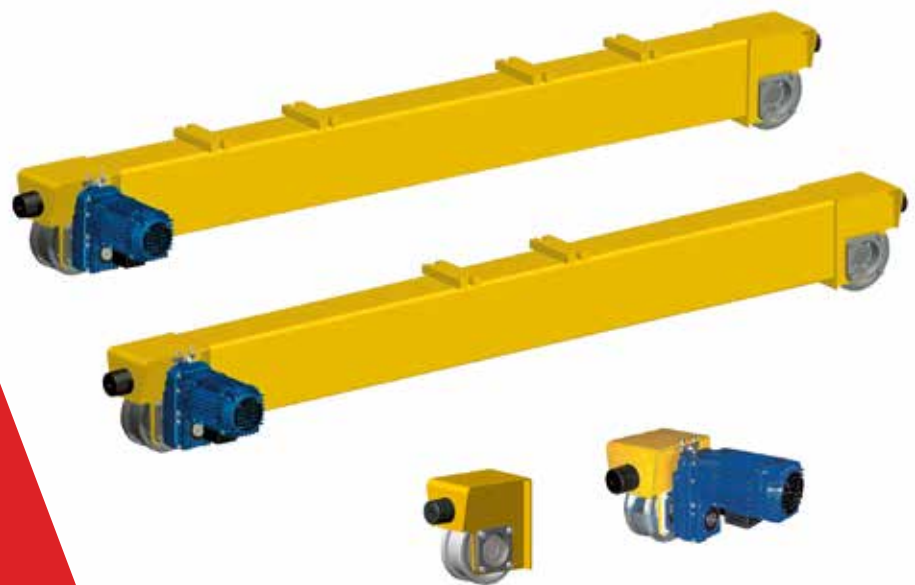


END-CARRIAGES FOR BRIDGE CRANES

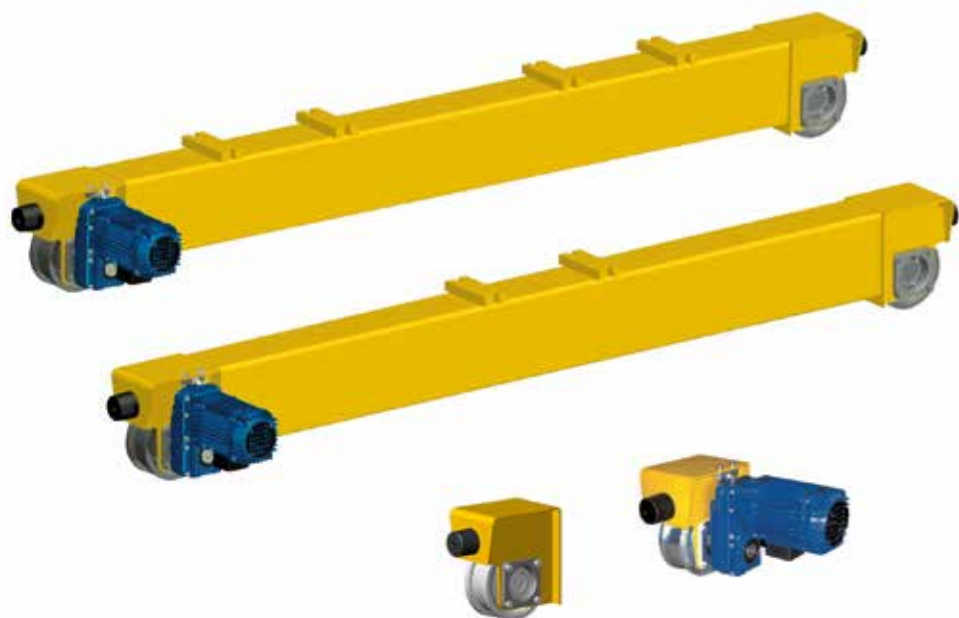
Wheel groups
DGT SERIES
Offset geared-motor
DGP SERIES



END-CARRIAGES FOR BRIDGE CRANES

The bridge crane end-carriages, equipped with "DGT" series wheel groups, coupled with "DGP" series offset geared motors, represent the most convenient offer for worldwide market requirements for handling masses up to 66,000 kg.

The bridge crane end-carriages, a completion of the range of DRH series electric wire rope hoists and DMK electric chain hoists, appreciated worldwide, complete the range and solutions offered by Donati Sollevamenti, with a view to always supplying the best solution to its customers while safeguarding the quality / price / performance ratio.



MAX

66.000 KG

The offer most in line with the worldwide market's needs for handling masses up to 66,000 kg protecting the customer's convenience



CONFORMITY TO NORMS AND REGULATIONS

APPLICABLE LEGISLATION

The bridge crane end-carriages are designed and produced by DONATI SOLLEVAMENTI S.r.l. in compliance with the "Essential Safety Requirements" stated in Attachment I of the Machinery Directive 2006/42/CE and are introduced onto the market accompanied by the Declaration of incorporation found in Attachment II B of the Directive.

APPLICABLE NORMS AND REGULATIONS

The following norms and technical principles have also been taken into consideration in the design and manufacturing of the **end-carriages for bridge cranes**:

- ▶ EN ISO 12100/2010 "Fundamental concepts on general engineering principles"
- ▶ EN ISO 13849-1/2008 "General principles for design"
- ▶ EN 60529/97 "Degrees of protection for casings (IP Codes)"
- ▶ ISO 4301-1/88 "Classifications for lifting equipment"
- ▶ ISO 8306/85 "Tolerances for cranes and tracks"
- ▶ FEM 1.001/98 "Calculations for lifting equipment"
- ▶ FEM 9.511/86 "Classification of mechanisms"
- ▶ FEM 9.683/95 "Criteria of choice for lifting and travel motors"
- ▶ FEM 9.755/93 "Safety work periods"

SERVICE CLASSIFICATION:

The structural elements and mechanisms on the **end-carriages for bridge cranes** are classified in various service groups, in conformity with specifications stipulated under ISO 4301.

PROTECTION AND SHEATHING OF ELECTRICAL PARTS:

- ▶ Sliding motors: protection IP55 (motor) - IP23 (brake); class "F" insulation
- ▶ Limit switch: minimum protection IP65; max. insulation voltage 500 V
- ▶ Protections and insulations differing from the standard, which can be supplied on request.

ELECTRICAL POWER:

- ▶ The **end-carriages for bridge cranes** are designed to be powered through three-phase alternating current: 400 V - 50Hz in accordance with IEC 38-1.
- ▶ Different voltage and frequency specifications from the standard can be supplied on request.

ENVIRONMENTAL CONDITIONS FOR STANDARD USAGE:

- ▶ Operating temperature: minimum - 10° C; maximum + 40°C
- ▶ Maximum relative humidity: 80% - Maximum altitude 1000 m above sea level
- ▶ Standard **end-carriages for bridge cranes** must be installed in a well-ventilated working environment, free of corrosive steams (acidic steams, saline mists, etc.), and are designed to operate in a covered environment, protected from atmospheric elements.
- ▶ Special machine models designed for non-standard environmental conditions, or for operation outdoors, can be supplied on request.

NOISE EMISSIONS - VIBRATIONS:

- ▶ Noise emission levels emanating from the **end-carriages** during running operations, whether empty or fully loaded, are in all cases inferior to a value of **80 dB (A)**, as measured at a distance of 1 m and 1.6 m from the ground. The incidence of environmental characteristics such as the transmission of sound through metallic structures, reflection caused by combined machinery and surrounding walls, is not taken into consideration in the value indicated.
- ▶ Vibrations produced by the **end-carriages** during running operations are not considered dangerous for the health and wellbeing of personnel operating the lifting equipment on which the units are installed.



END-CARRIAGES FOR BRIDGE CRANES

DONATI **end-carriages** are designed for handling operations on bridge crane rails:

- ▶ at single running speed from 3.2 to 25 m/min;
- ▶ at two running speeds, from 12.5/3.2 to 80/20 m/min;

Operating on:

- ▶ single girder, with a capacity of up to 20,000 kg and gauge of up to 25 m;
- ▶ double girder, with a capacity of up to 40,000 kg and gauge of up to 27 m.

Designed and built on the principle of modular components assembled together in relation to their specific use, they are equipped with **drive units** comprising **"DGT" series wheel groups**, which are combined with **"DGP" series offset geared motors**.

They are configured in 6 sizes, where the basic components are:

- ▶ **6 "DGT" series drive wheel group sizes**
(Ø 125, Ø 160, Ø 200, Ø 250, Ø 315 and Ø 400/400 R)
- ▶ **4 "DGP" series offset reducers sizes**
(DGP 0, DGP 1, DGP 2 and DGP 3)
- ▶ **4 self-braking motors sizes**
(motor 71, motor 80, motor 100 and motor 112)

OPERATING LIMITATIONS FOR END-CARRIAGES ON SINGLE GIRDER OR DOUBLE GIRDER BRIDGE CRANES, IN RELATION TO SPAN

SIZE "DGT"	END-CARRIAGES TYPE		SPAN (m) SINGLE GIRDER M OR DOUBLE GIRDER B BRIDGE CRANE																										
	WHEEL		6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27					
	Ø R (mm)	BASIS PR (mm)																											
1	125	1800	M																										
		2400	B										M	B															
		3300											M					B											
2	160	1800	M																										
		2400	B										M	B															
		3300											M					B											
3	200	2100	M																										
		2700	B										M	B															
		3600											M					B											
4	250	2100	M																										
		2700	M	B	B										M	B													
		3600											M					B											
		3600 R											M																
5	315	2400	M																										
		3900											B																
6	400	3900											B																
		400R	3900 R											B															

"DGT" WHEELS		"DGP" SERIES OFFSET GEARED MOTORS				
SIZE	Ø (mm)	"DGP" REDUCERS SIZE 0	"DGP" REDUCERS SIZE 1	"DGP" REDUCERS SIZE 2	"DGP" REDUCERS SIZE 3	
1	125					
2	160	Motor size 71				
3	200	=	Motor size 71	Motor size 80		
4	250	=				
5	315	=	=	=		
6	400	=	=	=		
	400R	=	=	=		

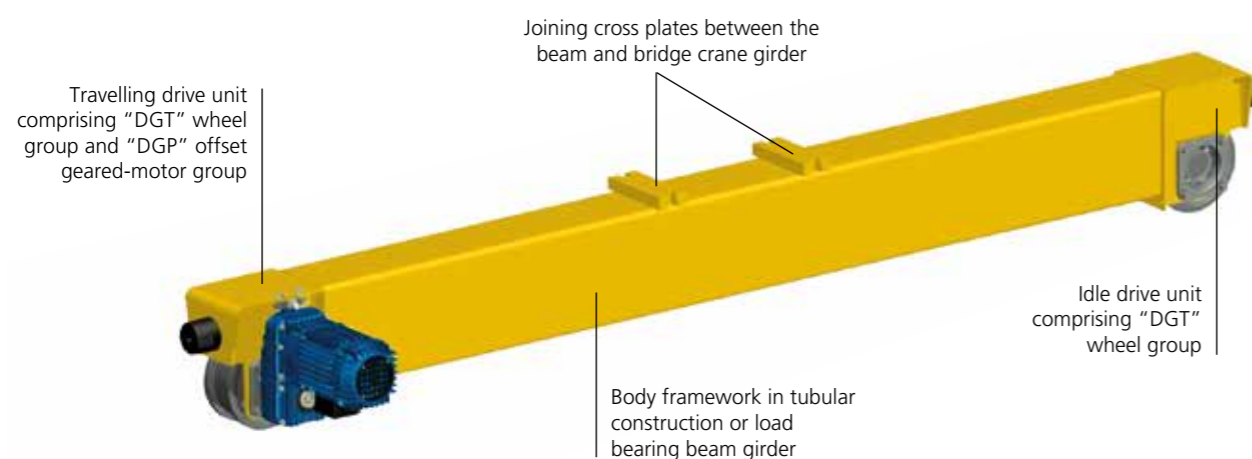
COMPONENTS ON END-CARRIAGES FOR BRIDGE CRANES

THE MAIN COMPONENTS ON END-CARRIAGES FOR BRIDGE CRANES ARE THE:

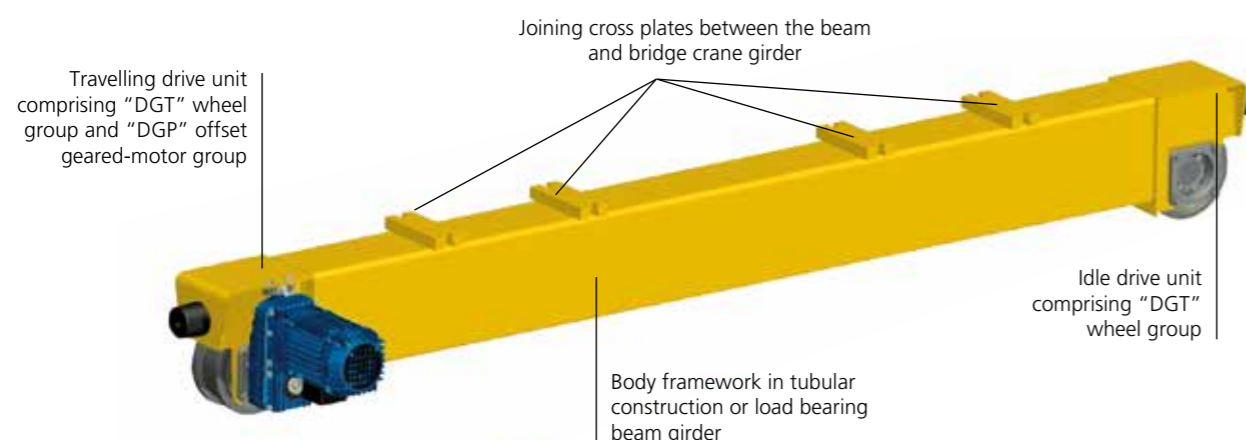
END-CARRIAGE FRAMEWORK:

- ▶ The load-bearing structure is made from a rectangular tubular section.
- ▶ The bridge crane girders are fixed to the end-carriage structure using a system of high-resistance bolts and a pin centring system.

END-CARRIAGE FOR SINGLE GIRDER BRIDGE CRANE

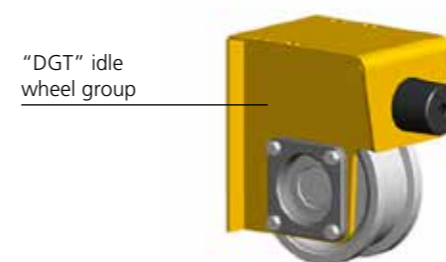


END-CARRIAGE FOR DOUBLE GIRDER BRIDGE CRANE



"DGT" SERIES WHEEL GROUPS

- ▶ Drive wheels Ø 125, Ø 160, Ø 200, Ø 250 and Ø 315 are carbon steel moulded. Sliding wheels Ø 400 and Ø 400 R are in spheroidal cast iron.
- ▶ All wheels groups revolve on permanently lubricated radial bearings, with the exception of the extra load capacity Ø 400 R wheel group, which is fitted with roller bearings.
- ▶ Available in idle operation or ready for drive operation combined with an offset geared-motor.
- ▶ In drive operation, the direct connection is coaxial between the offset geared-motor output shaft and the grooved hub on the drive wheel ensures a high level of operating safety and reliability.
- ▶ The wheel group is available as standard with a doubleflange version and can, on request, be supplied with different sliding band widths depending on the type of rail it runs on.
- ▶ Both in idle and drive operation, the wheel groups are supported and contained within an electro-welded steel structure that acts as a support casing for the entire group, and as a joining element between the end carriage frame on which the wheel group is assembled.

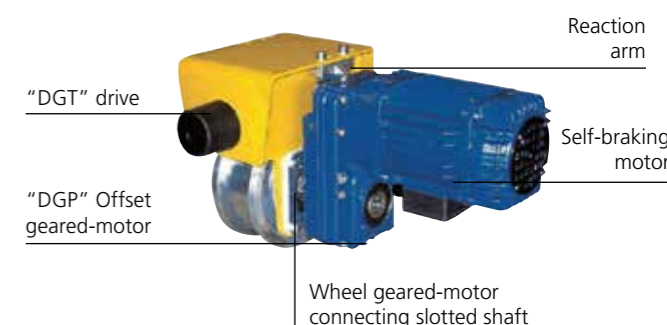


THE CONNECTION PLATE (SINGLE GIRDER) OR PLATES (DOUBLE GIRDER) FIX THE END-CARRIAGE TO THE CRANE'S GIRDER OR GIRDERS:

Specially designed connection plates fix the end-carriages to the girder/s of the bridge crane. Built in steel plating in different sizes, they are welded to the bridge crane girders, whether tubular or plated sectioned, laterally joined or fixed to the travelling beam structures.

"DGP" SERIES OFFSET GEARED-MOTORS

- ▶ **Reducers** are designed as an "offset geared-motor" type with a concave shaft, featuring parallel axes with two or three stages of reduction, and permanent oil-bath lubrication.
- ▶ Engineered with cylindrical high resistance steel gears, featuring spiral teething, heat-treated, entirely supported on ball bearings.
- ▶ Sized to resist a lifetime of stress and wear, in accordance to the pertinent ISO service group.
- ▶ The connection between the geared-motor and drive wheel is guaranteed by a slotted shaft connecting the holes on both parts, while the geared-motor fastened to the wheel group makes use of a system comprising a reaction arm fastened to the wheel group, and an elastic counter bearing with rubber buffers and a setscrew. The entire geared-motor-wheel connection system guarantees both high quality running operation and maximum duration over time with low maintenance, thanks to the elimination of rigid connections.
- ▶ **The electric motors** are asynchronous, featuring progressive start-up, with standard ventilation, selfbraking with axial shifting of the rotor guaranteeing fast, reliable mechanical braking.
- ▶ Conical brakes are fitted with asbestos-free brake lining, featuring an extended braking surface.
- ▶ The brake block comprises a fan which ensures proper cooling for the brake and motor, shifting axially with the motor shaft; the brake function is activated automatically in the case of a power outage.
- ▶ The connection between the motor and offset gearedmotor features a joint contained within a couplinghousing.



ACCESSORIES (limit switches, towing arms, etc.):

The travel limit switch on the end-carriages, when supplied, is a rotating type with a double cross-rod ensuring for two-speed cranes a dual function of pre-deceleration and stopping in both directions, and is housed on the DGT drive unit.

TECHNICAL SPECIFICATIONS AND OPERATING LIMITATIONS FOR END-CARRIAGES FOR BRIDGE CRANES

For complete technical specifications on the end-carriages for bridge cranes, in relation to their intended operation, check and match the parameters limiting their operation.

The tables below provide a suitable means of verifying operating limits and specifications for end-carriages with wheel groups in combination with offset geared-motors and self-braking motors, in relation to the following user specifications for the bridge crane the end-carriages are installed on.

Operating parameters required for selecting end-carriages:

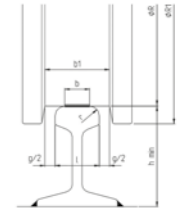
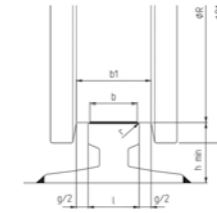
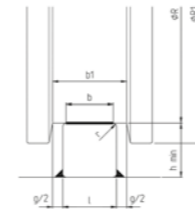
- ▶ type of bridge crane (single girder or double girder);
- ▶ load bearing capacity;
- ▶ span;
- ▶ ISO / FEM service group
- ▶ inflection point, with a nominal load on the beam's midsection;
- ▶ loads on the wheels;
- ▶ width and shape of the rail;
- ▶ running speed.

SPECIFICATIONS FOR RAILS AND MAXIMUM CONTACT AREA

Square laminated rail UNI 6013 - DIN 1013
Flat laminated rail UNI 6014 - DIN 1017

Burbak type rail - DIN 536

Vignole type rail - UNI 3141



TYPE Ø R	MAXIMUM REACTION RX. MAX.	WHEEL SPECIFICATIONS		RAIL			TYPE OF RUNNING RAIL AND MAXIMUM OPERATING CONTACT SURFACE - B (mm)							
				INTERNAL WIDTH (mm)	WIDTH b (mm)	h (mm)	SQUARE LAMINATED - UNI 6013 - DIN 1013 FLAT LAMINATED - UNI 6014 - DIN 1017		BURBAK - DIN 536		VIGNOLE - UNI 3141			
(mm)	(kg)	TIPO	b1	MAX.	MIN.	MAX.	l	b = l - 2r	TIPO	l	b = l - 2r	TIPO	l	b = l - 4/3r
125	3.670 36 kN	standard	50	40	35	30	40	38	=	=	=	=	=	=
		maximum	60	50	45	30	50	48	A 45	45	37	21 - 27	50	34
		special	70	60	55	30	60	58	A 55	55	45	36	60	44
160	4.893 48 kN	standard	55	45	40	30	40	38	A 45	45	37	=	=	=
		maximum	65	55	50	30	50	48	A 55	55	45	21 - 27	50	34
		special	80	70	65	30	70	68	A 65	65	53	46 50	65 67	46 49
200	7.340 72 kN	standard	60	50	45	30	50	48	A 45	45	37	21 - 27	50	34
		maximum	70	60	55	30	60	58	A 55	55	45	30 36	56 60	40 44
		special	90	80	75	30	80	78	A 75	75	59	60	72 ⁽¹⁾	55
250	10.805 106 kN	standard	70	60	55	30	60	58	A 55	55	45	30 36	56 60	40 44
		maximum	80	70	65	30	70	68	A 65	65	53	46 50	65 67	46 49
		special	100	90	85	30	90	88	A 75	75 ⁽¹⁾	59	=	=	=
315	14.679 144 kN	standard	75	65	60	40	60	58	A 65	65	53	36 46	60 65	44 47
		maximum	85	75	70	40	70	68	A 75	75	59	50 60	67 ⁽¹⁾ 72	48 55
		special	110	100	95	40	100	98	A 100	100	80	=	=	=
400	18.960 186 kN	standard	85	75	70	40	70	68	A 75	75	59	50 60	67 ⁽¹⁾ 72	48 55
		maximum	95	85	80	40	80	78	=	=	=	=	=	=
400R	30.580 ⁽²⁾ 300 kN	special	115	100	95	40	100	98	A 100	100	80	=	=	=

The clearance between the internal width of the wheel and the maximum rail width must be contained within: slack ≥ 10 mm and ≤ 15 mm

(1) wheel with increased clearance = 18 mm

(2) the Ø 400 R wheel is sized identical to the Ø 400 wheel but allows for an increased reaction due to its roller bearings

Recommended rails appear in red, together with operating contact surface values, verified in relation to maximum static reaction

OPERATING LIMITS FOR WHEELS IN RELATION TO THE RAIL'S OPERATING CONTACT SURFACE AND RUNNING SPEED

The following diagrams (pages 12, 13 and 14) illustrate average admissible reactions $R_{ave.}$ (expressed in kg) on drive unit wheels, in relation to the running speed and to the operating width "b", as specified in the table on page 11. The correct choice of wheel is based on the average effective reaction $R_{ave.}$ effettiva, exerted on the wheel.

This value is derived from the following equation:

$$R_{ave.} = \frac{2 * R_{max.} + R_{min.}}{3}$$

where $R_{max.}$ is the most unfavourable load condition, equal to:

$$R_{max.} = \frac{M1}{4} + \left(\frac{M2+P}{2} \right) * \left(1 - \frac{a}{s} \right)$$

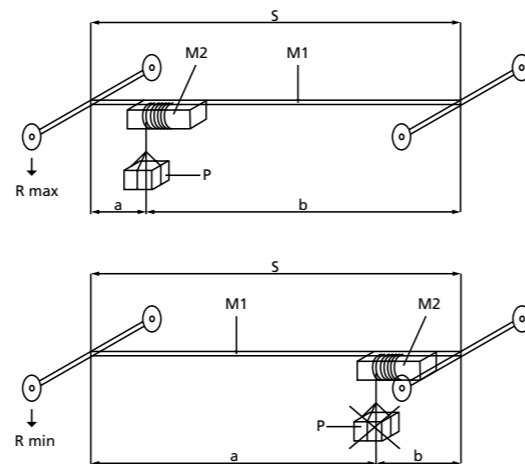
while the minimum reaction $R_{min.}$ is:

$$R_{min.} = \frac{M1}{4} + \frac{M2}{2} * \frac{a}{s}$$

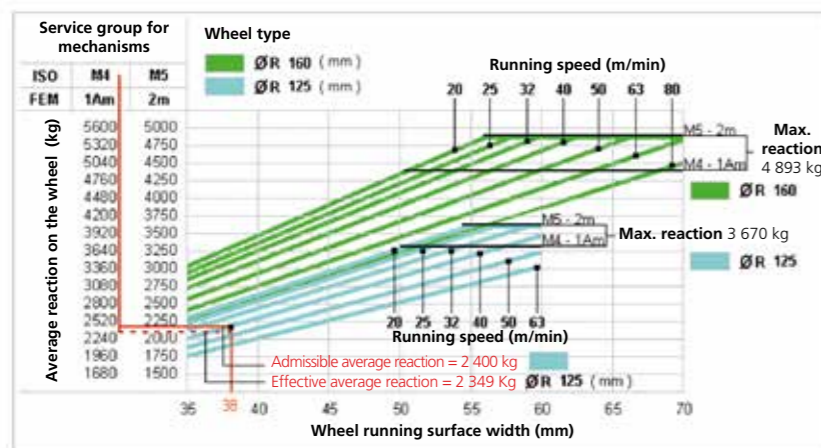
where: $M1$ = crane mass, i.e. its proper weight (crane's weight including accessories), expressed in kg

$M2$ = hoist/trolley mass, i.e. their proper weight, expressed in kg

P = nominal crane capacity, expressed in kg



ADMISSIBLE AVERAGE REACTIONS OF WHEELS Ø 125 AND 160, IN RELATION TO THE RAIL WIDTH AND RUNNING SPEED



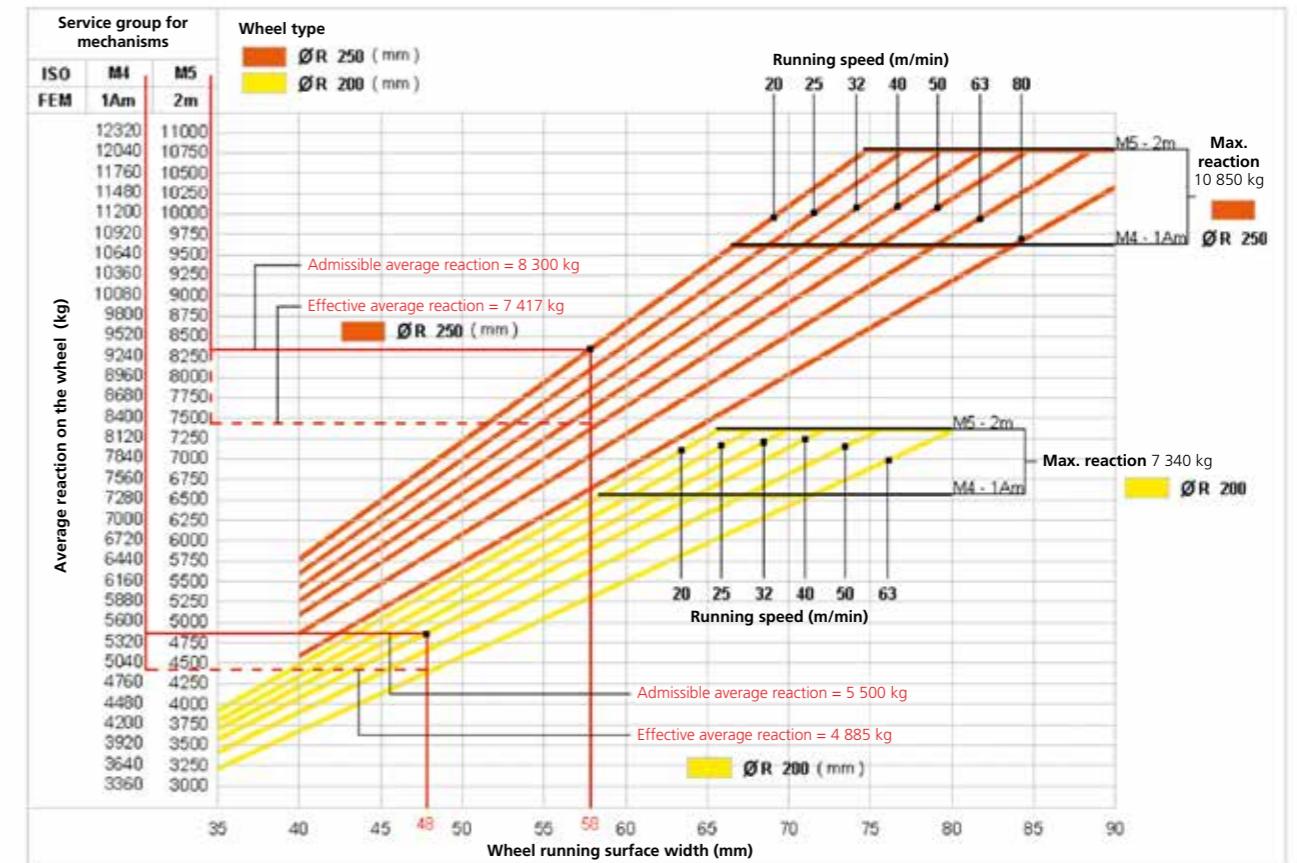
Example of verification of suitability for a Ø 125 wheel (see example 1 on page 36)

Data calculated:

- ▶ Rail operating width: $b = 38$ mm
- ▶ Travelling speed: 40/10 m/min;
- ▶ Service group: ISO M4 (FEM 1Am)
- ▶ Average effective reaction: $R_{ave.} = 2.349$ kg
- ▶ Maximum effective reaction: $R_{max. eff.} = 3.203$ kg

The average admissible reaction is ≈ 2.400 kg > than the average effective reaction of 2.349 kg the wheel is subjected to;
The maximum admissible reaction is ≈ 3.670 kg > than the maximum effective reaction of 3.203 kg

AVERAGE ADMISSIBLE REACTIONS FROM WHEELS Ø 200 AND 250, IN RELATION TO THE OPERATING WIDTH AND TRAVELLING SPEED



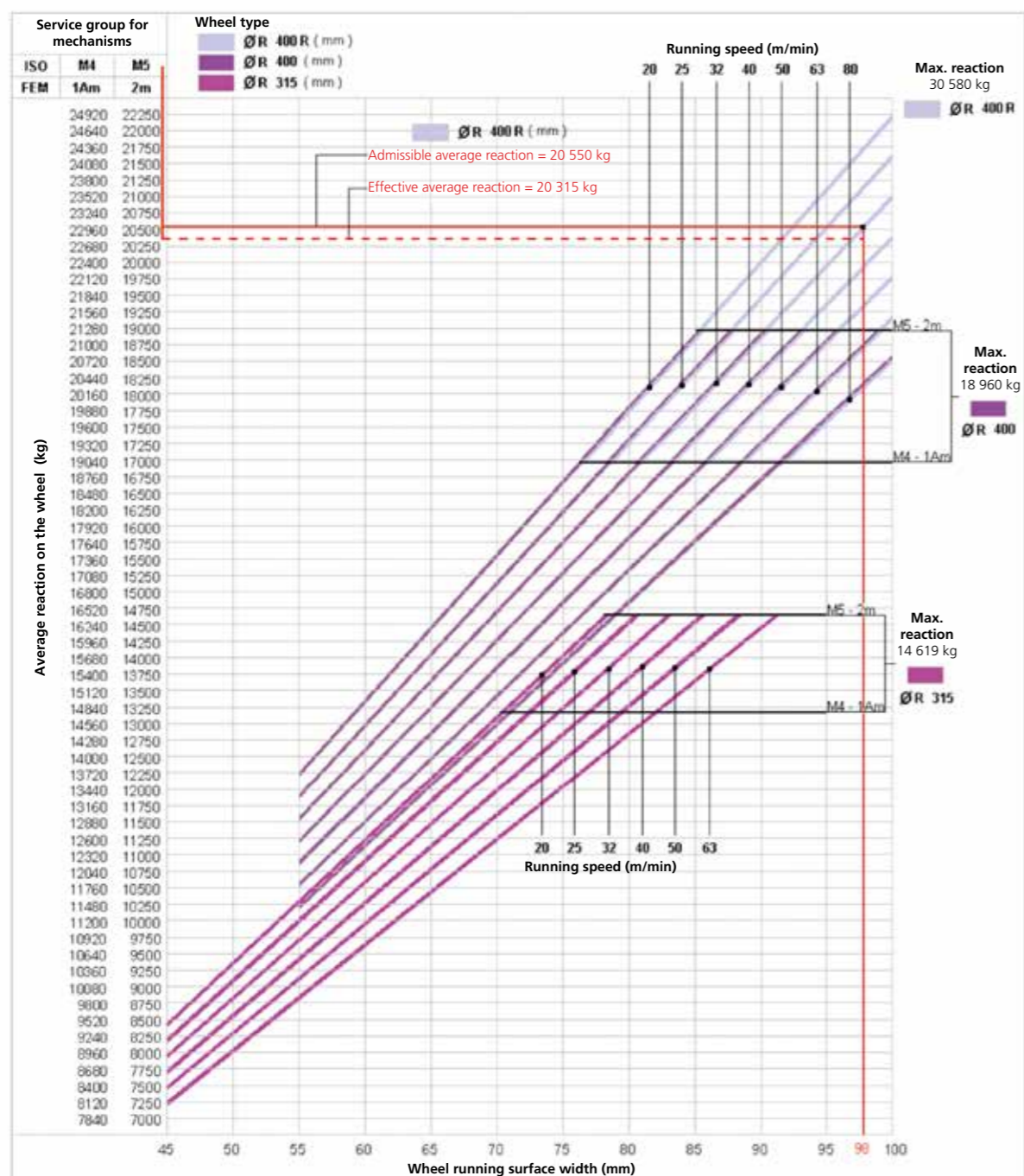
Example of verification of suitability for a Ø 200 wheel (see example 2 on page 26)

Data calculated:

- ▶ Rail operating width: $b = 48$ mm
- ▶ Travelling speed: 40/10 m/min;
- ▶ Service group: ISO M4 (FEM 1Am)
- ▶ Average effective reaction: $R_{ave.} = 4.885$ kg
- ▶ Maximum effective reaction: $R_{max. eff.} = 6.581$ kg

The average admissible reaction is ≈ 5.500 kg > than the average effective reaction of 4.885 kg the wheel is subjected to;
The maximum admissible reaction is ≈ 7.340 kg > than the maximum effective reaction of 6.581 kg

AVERAGE ADMISSIBLE REACTIONS FROM WHEELS Ø 315 AND 400, IN RELATION TO THE RAIL WIDTH AND TRAVELLING SPEED



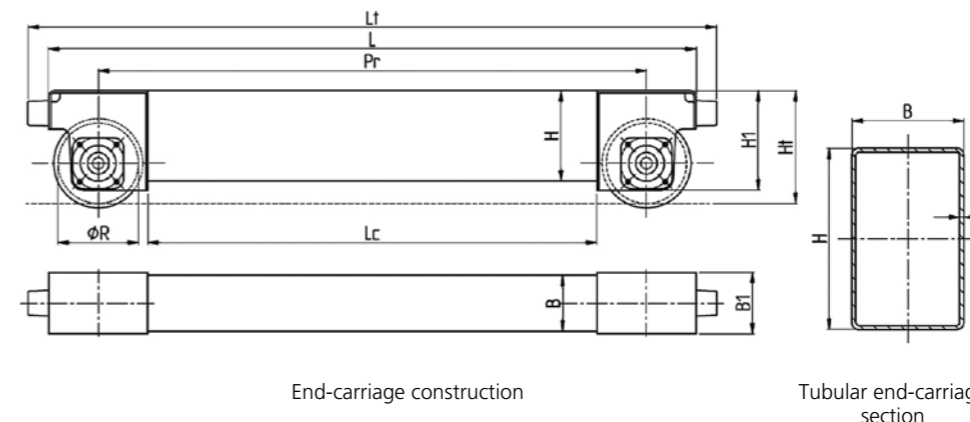
Example of verification of suitability for a Ø 315 wheel (see example 1 on page 26)

Data calculated:

- ▶ Rail operating width: $b = 58$ mm
- ▶ Travelling speed: 40/10 m/min;
- ▶ Service group: ISO M5 (FEM 2m)
- ▶ Average effective reaction: $R_{ave.} = 9.202$ kg
- ▶ Maximum effective reaction: $R_{max. eff.} = 11.963$ kg

The average admissible reaction is 9.900 kg > than the average effective reaction of 9.202 kg the wheel is subjected to;
The maximum admissible reaction is 14.679 kg > than the maximum effective reaction of 11.963 kg

GEOMETRICAL SPECIFICATIONS BASED ON END-CARRIAGE FOR SINGLE OR DOUBLE GIRDER BRIDGE CRANES



END-CARRIAGE TYPE	WHEEL		END-CARRIAGE DIMENSIONAL DATA (mm)									INERTIAL DATA ON TUBULAR SECTION							
	SIZE "DGT"	Ø R (mm)	BASIS PR (mm)	Lc	L	Lt	S	B	H	B1	H1	Ht	WT (cm³)	JX (cm⁴)	WX (cm³)	JY (cm⁴)	WY (cm³)	AREA (cm²)	WEIGHT (kg/m)
1	125	1800	2400	1630	1970	2030	5	120	220	160	225	233	231.8	2067.0	187.9	811.7	135.3	32.23	25.3
		3300	3130	3470	3530	8	343.0						3200.0	291.0	1230.0	205.0	51.2	40.2	
		3600	3340	3860	3990	10	775.0						7740.0	595.0	4350.0	483.0	82.9	65.1	
2	160	1800	2400	1590	2010	2110	6.3	180	260	180	260	275	524.0	5170.0	397.0	2930.0	325.0	53.4	41.9
		3300	3090	3510	3610	10	775.0						7740.0	595.0	4350.0	483.0	82.9	65.1	
		3600	3290	3910	4040	16	1470.0						17390.0	1160.0	9110.0	911.0	147.0	115	
3	200	2100	2700	1840	2360	2490	6.3	180	260	200	290	315	524.0	5170.0	397.0	2930.0	325.0	53.4	41.9
		3600	3340	3860	3990	10	775.0						7740.0	595.0	4350.0	483.0	82.9	65.1	
		3600 R	3290	3910	4040	16	1470.0						17390.0	1160.0	9110.0	911.0	147.0	115	
4	250	2100	2700	1790	2410	2540	6.3	200	300	230	335	370	681.0	7830.0	522.0	4190.0	419.0	61.0	47.9
		3600	3290	3910	4040	10	1020.0						11820.0	788.0	6280.0	628.0	94.9	74.5	
		3600 R	3290	3910	4040	16	1470.0						17390.0	1160.0	9110.0	911.0	147.0	115	
5	315	2400	3900	2010	2790	2950	8	250	350	260	385	437	1250.0	16450.0	940.0	9800.0	784.0	92.8	72.8
		3900	3510	4290	4450	12.5	1840.0						24420.0	1400.0	14440.0	1160.0	142.0	112.0	
		3900 R	3430	4370	4570	12.5	2590.0						38450.0	1920.0	24610.0	1640.0	167.0	131.0	
6	400	3900	3900 R	3430	4370	4570	16	300	400	290	440	495	3180.0	56183.4	3015.0	31187.5	2079.0	234.2	183.8
		3900 R	3430	4370	4570	16	3180.0						56183.4	3015.0	31187.5	2079.0	234.2	183.8	

* Reinforced tubular

END-CARRIAGES FOR DOUBLE GIRDER CRANES

OPERATING LIMITATIONS FOR END-CARRIAGES ON DOUBLE GIRDER BRIDGE CRANES BASED ON: CAPACITY - ISO/FEM GROUP - SPAN

CAPACITY (kg)	ISO/FEM GROUP	SPAN (m)																											
		6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27						
1000	M4/1Am M5/2m																												
1250	M4/1Am M5/2m																												
1600	M4/1Am M5/2m																												
2000	M4/1Am M5/2m																												
2500	M4/1Am M5/2m								1 - 125 - 2400																				
3200	M4/1Am M5/2m																												
4000	M4/1Am M5/2m																												
5000	M4/1Am M5/2m																												
6300	M4/1Am M5/2m																												
8000	M4/1Am M5/2m							2 - 160 - 2400																					
10000	M4/1Am M5/2m																												
12500	M4/1Am M5/2m																												
16000	M4/1Am M5/2m																												
20000	M4/1Am																												
25000	M4/1Am M5/2m																												
32000	M4/1Am																												
40000	M4/1Am																												

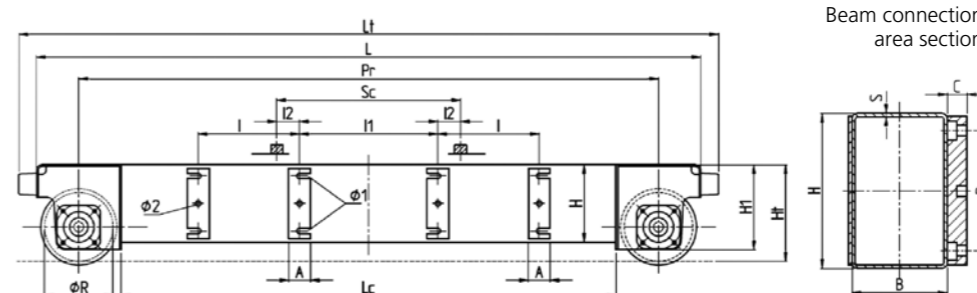
Admissible travelling mass from beams on DOUBLE GIRDER bridge crane [Travelling mass (kg) = capacity + crane weight + weight of trolley/hoist]

1-125	2-160	3 - 200	4 - 250	5 - 315	6 - 400	6 - 400R
2400	3300	2400	3300	2700	3600	2700
9.300	10.400	11.500	13.200	17.100	18.800	25.000
				25.500	35.900	46.000
					3900	3900 R
						62.000

Note: operating limitations determined using Donati components (hoist, trolley, etc.) and sectioned beams sized as per arrow $a = \text{Span} / 750$

END-CARRIAGES FOR DOUBLE GIRDER CRANES WITH CONNECTION PLATES TO "BRIDGE GIRDERS" "LATERAL" EXECUTION

Joining of beam girders in "Lateral" configuration



END-CARRIAGES TYPE	BEAM CODES BASED ON THE GAUGE OF THE DOUBLE GIRDER TROLLEY, TYPE OF GIRDERS ON THE BRIDGE CRANE AND MAX. GIRDER SPAN					DIMENSION (mm)								WEIGHT (kg)
	DOUBLE GIRDER TROLLEY GAUGE		BRIDGE CRANE GIRDERS		BEAM CODE	(FOR OTHER DIMENSIONS SEE PAGE 15)								
	Sc (mm)	TYPE	MAX. SPAN (mm)			I	I1	I2	A	C	D	Ø1	Ø2	
1 - 125 - 2400	1000	Box Girder	305	W124H1..	360	870	65	60	25	165	17	20	132	
		HE	370	W124H2..	430	865	67.5							
	1200	Box Girder	305	W124H4..	360	1070	65							
		HE	370	W124H5..	430	1065	67.5							
	1 - 125 - 3300	1000	Box Girder	305	W133H1..	360	870							65
			HE	370	W133H2..	430	865							67.5
1200			Box Girder	305	W133H3..	510	805	97.5						
			HE	300	W133H4..	360	640	180						
1400			Box Girder	305	W133H5..	360	1070	65						
			HE	370	W133H6..	430	1065	67.5						
2 - 160 - 2400		1000	Box Girder	305	W133H7..	360	1270	65						
			HE	370	W133H8..	430	1265	67.5						
			HE	450	W133H9..	510	1205	97.5						
		1200	Box Girder	305	W133HG..	360	1040	180						
			Box Girder	305	W224H1..	360	870	65						
			HE	370	W224H2..	430	865	67.5						
2 - 160 - 3300	1000	Box Girder	305	W224H4..	360	1070	65							
		HE	370	W224H5..	430	1065	67.5							
		HE	300	W224HD..	360	840	180							
		1200	Box Girder	370	W233H2..	430	865	67.5						
			HE	450	W233H3..	510	816	92						
		1400	Box Girder	300	W233HA..	360	640	180						
	HE		370	W233H5..	430	1065	67.5							
	3 - 200 - 2700	1000	Box Girder	450	W233H6..	510	1016	92						
			HE	300	W233HD..	360	840	180						
			HE	370	W233H8..	430	1265	67.5						
		1200	Box Girder	450	W233H9..	510	1216	92						
			HE	300	W233HG..	360	1040	180						
HE			360	W327H1..	420	830	85							
3 - 200 - 3900	1000	Box Girder	410	W327H2..	480	846	77							
		HE	300	W327HA..	420	580	210							
		HE	360	W327H4..	420	1030	85							
	1200	Box Girder	410	W327H5..	480	1046	77							
		HE	300	W327HD..	420	780	210							
		HE	360	W327H7..	420	1230	85							
1400	Box Girder	410	W327H8..	480	1246	77								
	HE	300	W327HG..	420	980	210								

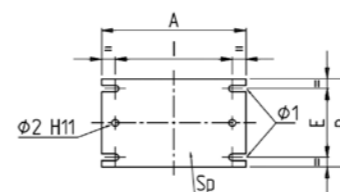
**END-CARRIAGES FOR DOUBLE GIRDER CRANES WITH CONNECTION PLATES TO "BRIDGE GIRDERS"
"LATERAL + ON THE TOP" EXECUTION**

END-CARRIAGES TYPE	BEAM CODES BASED ON THE GAUGE OF THE DOUBLE GIRDER TROLLEY, TYPE OF GIRDERS ON THE BRIDGE CRANE AND MAX. GIRDER SPAN			DIMENSION (mm)													WEIGHT (kg)
	DOUBLE GIRDER TROLLEY GAUGE Sc (mm)	BRIDGE CRANE GIRDERS MAX. SPAN BOX GIRDER (mm)	BEAM CODE	I	I1	I2	F	F1	A	C	D	E	G	Ø1	Ø2		
4 - 250 - 2700	1000	410	W427N1..	480	846	77	522	804									
		490	W427N2..	560	846	77	602	804									
	1200	410	W427N4..	480	1046	77	522	1004									
4 - 250 - 3600	1000	490	W427N5..	560	1046	77	602	1004									
		565	W436N3..	640	841	79.5	682	799	80	30	235	190	148	25	25		
	1200	490	W436N5..	560	1046	77	602	1004									
		565	W436N6..	640	1041	79.5	682	999									
	1400	490	W436N8..	560	1246	77	602	1204									
		565	W436N9..	640	1241	79.5	682	1199									
5 - 315 - 3900	1000	410	W539N1..	500	826	87	542	784									
		490	W539N2..	580	826	87	622	784									
		615	W539N3..	710	805	97.5	752	763									
	1200	410	W539N4..	500	1026	87	542	984									
		490	W539N5..	580	1026	87	622	984	100	40	270	220	178	29	32		630
		615	W539N6..	710	1005	97.5	752	963									
	1400	410	W539N7..	500	1226	87	542	1184									
		490	W539N8..	580	1226	87	622	1184									
		615	W539N9..	710	1205	97.5	752	1163									
6 - 400 - 3900	1000	410	W639N1..	500	826	87	542	784									
		490	W639N2..	580	826	87	622	784									
		615	W639N3..	710	805	97.5	752	763									
	1200	410	W639N4..	500	1026	87	542	984									
		490	W639N5..	580	1026	87	622	984									
		615	W639N6..	710	1005	97.5	752	963	100	40	310	250	208	34	32		810
1400	410	W639N7..	500	1226	87	542	1184										
	490	W639N8..	580	1226	87	622	1184										
	615	W639N9..	710	1205	97.5	752	1163										
6 - 400 - 3900R	1400	410	W640N7..	500	1226	87	542	1184									
		490	W640N8..	580	1226	87	622	1184									
		615	W640N9..	710	1205	97.5	752	1163									

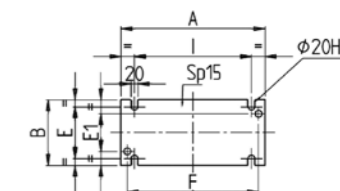
Referred partial codes are applied to couples of end-carriages without counterplates. In case of couples of end-carriages with counterplates, replace letter **N**, in fifth position, with letter **M**. The weights given in the table refer to the individual end-carriage.

GEOMETRIC SPECIFICATIONS FOR "GIRDER - BEAM" CONNECTION PLATES FOR SINGLE AND DOUBLE GIRDER BRIDGE CRANES

Connection plate for girder positioned laterally to the beam



Connection plate for girder on the top of the beam



END-CARRIAGE TYPE		MAX. BEAM WIDTH	PLATE POSITIONED Laterally TO THE BEAM									PLATE SUPPORTED ON THE TOP OF THE BEAM							
SIZE "DGT"	Ø WHEEL (mm)		L (mm)	TYPE	DIMENSIONS (mm)					WEIGHT (kg)	TYPE	DIMENSIONS (mm)					WEIGHT (kg)		
		A			I	B	Ø1	E	Ø2			Sp	F	A	I	B		E	E1
1	125	305	L11	420	360						8.4	A 11	402	440	360				8.0
		370	L12	490	430	220	18	165	20	12	9.9	A 12	472	510	430	160	120	78	9.3
		450	L13	570	510						11.6	A 13	552	590	510				10.8
2	160	305	L21	420	360						9.6	A 21	402	440	360				9.0
		370	L22	490	430	250	20	190	20	12	11.2	A 22	472	510	430	180	140	98	10.5
		450	L23	570	510						13.1	A 23	552	590	510				12.2
3	200	360	L31	500	420						14.7	A 31	462	500	420				11.5
		410	L32	560	480	260	22	195	25	15	16.5	A 32	522	560	480	200	160	118	13.0
		500	L33	640	560						19.0	A 33	602	640	560				14.7
4	250	410	L41	560	480						19.1	A 41	522	560	480				14.8
		490	L42	640	560	300	26	235	25	15	21.9	A 42	602	640	560	230	190	148	17.0
		565	L43	720	640						24.7	A 43	682	720	640				19.2
5	315	410	L51	600	500						31.6	A 51	542	580	500				17.4
		490	L52	680	580	350	30	270	32	20	36.0	A 52	622	660	580	260	220	178	20.0
		615	L53	810	710						43.2	A 53	752	790	710				23.8
6	400	410	L61	600	500						36.0	A 61	542	580	500				19.5
		490	L62	680	580	400	36	310	32	20	41.1	A 62	622	660	580	290	250	208	22.2
		615	L63	810	710						49.2	A 63	752	790	710				26.6

TRAVELLING MASSES AT 1 SPEED, BASED ON THE COMBINATION OF COMPONENTS

NOMINAL SPEED (m/min)	TRAVELLING MASS (kg) ISO SERVICE GROUP (FEM)		"DGT" WHEEL GROUP Ø (mm)	"DGP" GEARED-MOTORS		SELF-BRAKING MOTOR SPECS		CODES FOR COMPONENTS	
	M4 (1Am)	M5 (2m)		REDUCER TYPE	MOTOR TYPE	POLES (N°)	POWER (kW)	"DGT" DRIVE WHEEL GROUP	"DGP" GEARED-MOTOR
10	7.400	6.720	125	033	71K4CB	4	0.20	DGT1A0M10	P0M2B34KA0
	9.800	8.000	160	032	71K4CB	4	0.20	DGT2A0M10	P0M2B24KA0
	9.800	9.800		132	80K4CB	4	0.32	DGT2A0M30	P1M3B24KA0
	12.000	9.600	200	131	71K4CB	4	0.20	DGT3A0M10	P1M2B14KA0
	14.700	14.700		80K4CB	4	0.32		P1M3B14KA0	
	11.200	8.900	250	133	80K8L	8	0.16	DGT4A0M12	P1M3B38KA0
	21.600	18.000		232	80K4CB	4	0.32	DGT4A0M32	P2M3B24KA0
	21.600	21.600	315	231	100K4CB	4	0.80		P2M5B24KA0
	23.300	18.600		231	80K4CB	4	0.32	DGT5A0M12 (rh) DGT5A0M22 (lh)	P2M3B14KA0 P2M5B14KA0
	29.400	29.400	400	233	100K8L	8	0.40	DGT6A0M12 (rh) DGT6A0M22 (lh)	P2M5B38KA0
	33.100	26.500		331	112K8L	8	0.63	DGT6A0M32 (rh) DGT6A0M42 (lh)	P3M6B18AA0
	42.800	41.300	400 R	233	100K8L	8	0.40	DGT6A0M62 (rh) DGT6A0M72 (lh)	P2M5B38KA0
	33.100	=		331	112K8L	8	0.63	DGT6A0M82 (rh) DGT6A0M92 (lh)	P3M6B18AA0
	51.600	41.300		331	112K8L	8	0.63	DGT6A0M82 (rh) DGT6A0M92 (lh)	P3M6B18AA0

12,5	7.400	7.400	125	031	71K2CB	2	0.40	DGT1A0M10	P0M2B12KA0
	8.000	6.400	160	033	71K4CB	4	0.20	DGT2A0M10	P0M2B34KA0
	9.800	9.800		133	80K4CB	4	0.32	DGT2A0M30	P1M3B34KA0
	9.600	7.600	200	132	71K4CB	4	0.20	DGT3A0M10	P1M2B24KA0
	14.700	12.200		80K4CB	4	0.32		P1M3B24KA0	
	14.700	14.700	250	231	80K2CB	2	0.63	DGT3A0M30	P2M3B12KA0
	11.200	9.000		131	71K4CB	4	0.20	DGT4A0M12	P1M2B14KA0
	18.000	14.400	315	233	100K4CB	4	0.80	DGT4A0M32	P2M5B34KA0
	21.600	21.600		232	80K4CB	4	0.32	DGT5A0M12 (rh) DGT5A0M22 (lh)	P2M3B24KA0 P2M5B24KA0
	18.600	14.900	400	231	80K4CB	4	0.32	DGT6A0M12 (rh) DGT6A0M22 (lh)	P2M3B14KA0 P2M5B14KA0
	29.400	29.400		231	100K4CB	4	0.80		P2M5B14KA0
	20.800	16.600	400 R	231	100K4CB	4	0.80	DGT6A0M62 (rh) DGT6A0M72 (lh)	P2M5B14KA0
	41.400	33.100							

10	7.400	6.656	125	032	71K2CB	2	0.40	DGT1A0M10	P0M2B22KA0
	9.800	8.000	160	031	71K2CB	2	0.40	DGT2A0M10	P0M2B12KA0
	9.800	9.800		131	71K2CB	2	0.40	DGT2A0M30	P1M2B12KA0
	7.500	6.000	200	133	71K4CB	4	0.20	DGT3A0M10	P1M2B34KA0
	12.000	9.600		80K4CB	4	0.32		P1M3B34KA0	
	14.700	14.700	250	232	80K2CB	2	0.63	DGT3A0M30	P2M3B22KA0
	13.800	11.000		132	80K4CB	4	0.32	DGT4A0M12	P1M3B24KA0
	21.600	21.600	315	231	80K2CB	2	0.63	DGT4A0M32	P2M3B12KA0
	14.600	11.600		233	80K4CB	4	0.32	DGT5A0M12 (rh) DGT5A0M22 (lh)	P2M3B34KA0 P2M5B34KA0
	29.400	29.400	400	232	80K4CB	4	0.32	DGT6A0M12 (rh) DGT6A0M22 (lh)	P2M3B24KA0 P2M5B24KA0
	16.300	13.000		232	80K4CB	4	0.32		P2M3B24KA0
	41.400	33.100	400 R	232	100K4CB	4	0.80	DGT6A0M62 (rh) DGT6A0M72 (lh)	P2M5B24KA0
	41.400	33.100							

The specifications refer to a single geared-motor; in case of two or more geared-motors, multiply the travelling mass by the number of geared-motors used. Verify that in relation to the rail's running surface width (b), average reaction (R ave) is compatible with the values listed in diagram pages 12, 13 and 14. The values for travelling mass in red require a verification of average reaction (R ave.) on each wheel, which must not exceed the following Rx. max. values:

Ø 125 R ave. ≤ Rx max. ≤ 3.670 kg (36 kN)	Ø 160 R ave. ≤ Rx max. ≤ 4.893 kg (48 kN)	Ø 200 R ave. ≤ Rx max. ≤ 7.340 kg (72 kN)	Ø 250 R ave. ≤ Rx max. ≤ 10.805 kg (106 kN)	Ø 315 R ave. ≤ Rx max. ≤ 14.679 kg (144 kN)	Ø 400 R ave. ≤ Rx max. ≤ 18.960 kg (186 kN)	Ø 400 R R ave. ≤ Rx max. ≤ 30.580 kg (300 kN)
--	--	--	--	--	--	--

TRAVELLING MASSES AT 1 SPEED, BASED ON THE COMBINATION OF COMPONENTS

NOMINAL SPEED (m/min)	TRAVELLING MASS (kg) ISO SERVICE GROUP (FEM)		"DGT" WHEEL GROUP Ø (mm)	"DGP" GEARED-MOTORS		SELF-BRAKING MOTOR SPECS		CODES FOR COMPONENTS	
	M4 (1Am)	M5 (2m)		REDUCER TYPE	MOTOR TYPE	POLES (N°)	POWER (kW)	"DGT" DRIVE WHEEL GROUP	"DGP" GEARED-MOTOR
20	7.400	6.720	125	033	71K2CB	2	0.40	DGT1A0M10	P0M2B32KA0
	9.800	8.000	160	032	71K2CB	2	0.40	DGT2A0M10	P0M2B22KA0
	9.800	9.800		132	71K2L	2 with inv.	0.50	DGT2A0M30	P1M2B21KA0
	12.000	9.600	200		71K2CB	2	0.40		P1M2B12KA0
	14.700	12.200		131	71K2L	2 with inv.	0.50	DGT3A0M10	P1M2B11KA0
	14.700	14.700	250		80K2CB	2	0.63		P1M3B12KA0
	11.200	8.900		133	80K4CB	4	0.32	DGT4A0M12	P1M3B34KA0
	21.600	17.200	315	232	80K2CB	2	0.63	DGT4A0M32	P2M3B22KA0
	21.600	21.600		232	80K2L	2 with inv.	0.80		P2M3B21KA0
	23.300	18.600	400		80K2CB	2	0.63		P2M3B12KA0
	29.400	23.700		231	80K2L	2 with inv.	0.80	DGT5A0M12 (rh) DGT5A0M22 (lh)	P2M3B11KA0 P2M5B12KA0
	29.400	29.400	400 R	233	100K4CB	4	0.80	DGT6A0M12 (rh) DGT6A0M22 (lh)	P2M5B34KA0
	33.100	26.500		331	112K4C	4	1.25	DGT6A0M32 (rh) DGT6A0M42 (lh)	P3M6B14AA0
	42.800	41.300		331	112K4C	4	1.25	DGT6A0M62 (rh) DGT6A0M72 (lh)	P3M6B14AA0
33.100	26.500		233	100K4CB	4	0.80	DGT6A0M62 (rh) DGT6A0M72 (lh)	P2M5B34KA0	

25	6.700	5.360	125	034	71K2CB	2	0.40	DGT1A0M10	P0M2B42KA0
	7.400	6.700		134	80K2CB	2	0.63	DGT1A0M30	P1M3B42KA0
	7.400	6.700	160	033	71K2CB	2	0.40	DGT2A0M10	P0M2B32KA0
	9.800	8.000		133	71K2L	2 with inv.	0.50	DGT2A0M30	P0M2B31KA0
	9.800	9.800	200		80K2CB	2	0.63		P1M3B32KA0
	9.600	7.600		132	71K2CB	2	0.40	DGT3A0M10	P1M2B22KA0
	12.000	9.600	250	132	80K2CB	2	0.63		P1M2B21KA0
	14.700	12.000		132	80K2L	2 with inv.	0.80		P1M3B22KA0
	14.700	14.700	315		80K2L	2 with inv.	0.80		P1M3B21KA0
	11.200	8.900		131	71K2CB	2	0.40	DGT4A0M12	P1M2B12KA0
	13.800	11.000	400	131	71K2L	2 with inv.	0.50		P1M2B11KA0
	17.200	13.800		233	80K2CB	2	0.63	DGT4A0M32	P2M5B32KA0
	21.600	21.600	400 R	232	100K2CB	2	1.60		P2M5B32KA0
	18.600	14.900		232	80K2CB	2	0.63	DGT5A0M12 (rh) DGT5A0M22 (lh)	P2M3B22KA0 P2M5B22KA0
23.700	18.900	400	232	80K2L	2 with inv.	0.80		P2M3B21KA0	
29.400	29.400		231	100K2CB	2	1.60		P2M5B22KA0	
20.800	16.600	400 R	231	80K2CB	2	0.63		P2M3B12KA0	
26.500	21.200		231	80K2L	2 with inv.	0.80	DGT6A0M12 (rh) DGT6A0M22 (lh)	P2M3B11KA0 P2M5B12KA0	
41.400	33.100		231	100K2CB	2	1.60		P2M5B12KA0	
53.000	42.400		231	100K2L	2 with inv.	2.00	DGT6A0M62 (rh) DGT6A0M72 (lh)	P2M5B12KA0 P2M5B11KA0	
66.200	53.000								

The specifications refer to a single geared-motor; in case of two or more geared-motors, multiply the travelling mass by the number of geared-motors used. Verify that in relation to the rail's running surface width (b), average reaction (R ave) is compatible with the values listed in diagram pages 12, 13 and 14. The values for travelling mass in red require a verification of average reaction (R ave.) on each wheel, which must not exceed the following Rx. max. values:

Ø 125 R ave. ≤ Rx max. ≤ 3.670 kg (36 kN)	Ø 160 R ave. ≤ Rx max. ≤ 4.893 kg (48 kN)	Ø 200 R ave. ≤ Rx max. ≤ 7.340 kg (72 kN)	Ø 250 R ave. ≤ Rx max. ≤ 10.805 kg (106 kN)	Ø 315 R ave. ≤ Rx max. ≤ 14.679 kg (144 kN)	Ø 400 R ave. ≤ Rx max. ≤ 18.960 kg (186 kN)	Ø 400 R R ave. ≤ Rx max. ≤ 30.580 kg (300 kN)
--	--	--	--	--	--	--

TRAVELLING MASSES AT 2 SPEEDS, BASED ON THE COMBINATION OF COMPONENTS

Table with columns: NOMINAL SPEED (m/min), TRAVELLING MASS (kg) ISO SERVICE GROUP (FEM) (M4, M5), 'DGT' WHEEL GROUP (Ø), 'DGP' GEARED-MOTORS (REDUCER TYPE, MOTOR TYPE, POLES, POWER), SELF-BRAKING MOTOR SPECS, CODES FOR COMPONENTS ('DGT' DRIVE WHEEL GROUP, 'DGP' GEARED-MOTOR). Rows include various speed and mass combinations.

The specifications refer to a single geared-motor; in case of two or more geared-motors, multiply the travelling mass by the number of geared-motors used. Verify that in relation to the rail's running surface width (b), average reaction (R ave) is compatible with the values listed in diagram pages 12, 13 and 14. The values for travelling mass in red require a verification of average reaction (R ave.) on each wheel, which must not exceed the following Rx. max. values:

Table showing R ave. ≤ Rx max. values for different wheel diameters: Ø 125, Ø 160, Ø 200, Ø 250, Ø 315, Ø 400, Ø 400 R.

TRAVELLING MASSES AT 2 SPEEDS, BASED ON THE COMBINATION OF COMPONENTS

Table with columns: NOMINAL SPEED (m/min), TRAVELLING MASS (kg) ISO SERVICE GROUP (FEM) (M4, M5), 'DGT' WHEEL GROUP (Ø), 'DGP' GEARED-MOTORS (REDUCER TYPE, MOTOR TYPE, POLES, POWER), SELF-BRAKING MOTOR SPECS, CODES FOR COMPONENTS ('DGT' DRIVE WHEEL GROUP, 'DGP' GEARED-MOTOR). Rows include various speed and mass combinations.

The specifications refer to a single geared-motor; in case of two or more geared-motors, multiply the travelling mass by the number of geared-motors used. Verify that in relation to the rail's running surface width (b), average reaction (R ave) is compatible with the values listed in diagram pages 12, 13 and 14. The values for travelling mass in red require a verification of average reaction (R ave.) on each wheel, which must not exceed the following Rx. max. values:

Table showing R ave. ≤ Rx max. values for different wheel diameters: Ø 125, Ø 160, Ø 200, Ø 250, Ø 315, Ø 400, Ø 400 R.

TRAVELLING MASSES AT 2 SPEEDS, BASED ON THE COMBINATION OF COMPONENTS

NOMINAL SPEED (m/min)	TRAVELLING MASS (kg) ISO SERVICE GROUP (FEM)		"DGT" WHEEL GROUP Ø (mm)	"DGP" GEARED-MOTORS		SELF-BRAKING MOTOR SPECS		CODES FOR COMPONENTS				
	M4 (1Am)	M5 (2m)		REDUCER TYPE	MOTOR TYPE	POLES (N°)	POWER (kW)	"DGT" DRIVE WHEEL GROUP	"DGP" GEARED-MOTOR			
50/12.5	3.300	2.640	125	023	71K3L	2/8	0.40/0.09	DGT1A0M10	P0M2A33KA0			
	4.125	3.300			71K2L	2 with inv.	0.50		P0M2A31KA0			
	4.125	3.300			80K3C	2/8	0.50/0.12		P1M3A33AA0			
	5.197	4.157			80K3L	2/8	0.63/0.15		P1M3A33KA0			
	6.600	5.280			80K2L	2 with inv.	0.80		P1M3A31KA0			
	5.000	4.000			160	022	71K2L		2 with inv.	0.50	DGT2A0M10	P0M2A21KA0
	5.000	4.000	80K3C	2/8			0.50/0.12	P1M3A23AA0				
	6.300	5.000	80K3L	2/8			0.63/0.15	P1M3A23KA0				
	8.000	6.300	80K2L	2 with inv.			0.80	P1M3A21KA0				
	6.000	4.800	71K2L	2 with inv.			0.50	P1M2A11KA0				
	7.600	6.000	200	121			80K3L	2/8	0.63/0.15	DGT3A0M10		P1M3A13KA0
	9.400	7.600			80K2L	2 with inv.	0.80	P1M3A11KA0				
	14.700	12.000			100K3C	2/8	1.25/0.31	DGT3A0M30	P2M5A33AA0			
	14.700	14.700			100K3L	2/8	1.60/0.39		P2M5A33KA0			
	8.600	6.900			250	134	80K3L	2/8	0.63/0.15		DGT4A0M12	P1M3B43KA0
	10.800	8.600					80K2L	2 with inv.	0.80			P1M3B41KA0
	17.200	13.800	100K3C	2/8			1.25/0.31	DGT4A0M32	P2M5A23AA0			
	21.600	17.200	100K3L	2/8			1.60/0.39		P2M5A23KA0			
	21.600	21.600	100K2L	2 with inv.			2.00	P2M5A21KA0				
	9.200	7.400	315	221			80K3L	2/8	0.63/0.15	DGT5A0M12 (rh) DGT5A0M22 (lh)		P2M3A13KA0
	11.800	9.400			80K2L	2 with inv.	0.80	P2M3A11KA0				
	18.400	14.700			100K3C	2/8	1.25/0.31	DGT5A0M32 (rh) DGT5A0M42 (lh)	P2M5A13AA0			
	23.600	18.900			100K3L	2/8	1.60/0.39		P2M5A13KA0			
	29.400	29.400			112K3L	2/8	2.50/0.62	P3M6B33KA0				
	20.700	16.600			400	234	100K3C	2/8	1.25/0.31		DGT6A0M12 (rh) DGT6A0M22 (lh)	P2M5B43AA0
	26.500	21.200	100K3L	2/8			1.60/0.39	P2M5B43KA0				
	33.000	26.400	100K2L	2 with inv.			2.00	P2M5B41KA0				
	41.200	33.000	112K3L	2/8			2.50/0.62	DGT6A0M32 (rh) DGT6A0M42 (lh)	P3M6B23KA0			
	42.800	42.200	112K2L	2 with inv.			3.20		P3M6B21KA0			
	33.000	26.400	400 R	234			100K2L	2 with inv.	2.00	DGT6A0M62 (rh) DGT6A0M72 (lh)		P2M5B41KA0
	41.200	33.000			112K3L	2/8	2.50/0.62	DGT6A0M82 (rh) DGT6A0M92 (lh)	P3M6B23KA0			
	52.700	42.100			112K2L	2 with inv.	3.20		P3M6B21KA0			
	2.600	2.080			125	024	71K3L	2/8	0.40/0.09		DGT1A0M10	P0M2A43KA0
	3.250	2.600					71K2L	2 with inv.	0.50			P0M2A41KA0
	3.250	2.600					80K3C	2/8	0.50/0.12			P1M3A43AA0
	4.095	3.276	80K3L	2/8			0.63/0.15	P1M3A43KA0				
	5.200	4.160	80K2L	2 with inv.			0.80	P1M3A41KA0				
	5.000	4.000	160	123			80K3L	2/8	0.63/0.15	DGT2A0M30		P1M3A33KA0
	6.300	5.000			80K2L	2 with inv.	0.80	P1M3A31KA0				
	6.000	4.800			200	122	80K3L	2/8	0.63/0.15		DGT3A0M10	P1M3A23KA0
7.600	6.000	80K2L					2 with inv.	0.80	P1M3A21KA0			
12.000	9.600	100K3C					2/8	1.25/0.31	DGT3A0M30			P2M5A43AA0
14.700	12.000	100K3L					2/8	1.60/0.39				P2M5A43KA0
6.900	5.500	250	121	80K3L			2/8	0.63/0.15	DGT4A0M12	P1M3A13KA0		
8.600	6.900			80K2L			2 with inv.	0.80		P1M3A11KA0		
13.500	10.800			100K3C	2/8	1.25/0.31	DGT4A0M32	P2M5A33AA0				
17.200	13.800			100K3L	2/8	1.60/0.39		P2M5A33KA0				
21.600	17.200			100K2L	2 with inv.	2.00	P2M5A31KA0					
14.600	11.700			315	222	100K3C	2/8	1.25/0.31		DGT5A0M12 (rh) DGT5A0M22 (lh)	P2M5A23AA0	
18.700	14.900	100K3L	2/8			1.60/0.39	P2M5A23KA0					
23.400	18.700	100K2L	2 with inv.			2.00	P2M5A21KA0					
29.300	23.500	112K3L	2/8			2.50/0.62	DGT5A0M32 (rh) DGT5A0M42 (lh)	P3M6B43KA0				
29.400	29.400	112K2L	2 with inv.			3.20		P3M6B41KA0				
16.400	13.100	400	221			100K3C	2/8	1.25/0.31	DGT6A0M12 (rh) DGT6A0M22 (lh)		P2M5A13AA0	
21.000	16.800			100K3L	2/8	1.60/0.39	P2M5A13KA0					
32.800	26.200			112K3L	2/8	2.50/0.62	DGT6A0M32 (rh) DGT6A0M42 (lh)	P3M6B33KA0				
42.000	33.600			112K2L	2 with inv.	3.20		P3M6B31KA0				
32.800	26.200			400 R	333	112K3L	2/8	2.50/0.62		DGT6A0M82 (rh) DGT6A0M92 (lh)	P3M6B33KA0	
42.000	33.600					112K2L	2 with inv.	3.20			P3M6B31KA0	

The specifications refer to a single geared-motor; in case of two or more geared-motors, multiply the travelling mass by the number of geared-motors used. Verify that in relation to the rail's running surface width (b), average reaction (R ave) is compatible with the values listed in diagram pages 12, 13 and 14. The values for travelling mass in red require a verification of average reaction (R ave.) on each wheel, which must not exceed the following Rx. max. values:

Ø 125 R ave. ≤ Rx max. ≤ 3.670 kg (36 kN)	Ø 160 R ave. ≤ Rx max. ≤ 4.893 kg (48 kN)	Ø 200 R ave. ≤ Rx max. ≤ 7.340 kg (72 kN)	Ø 250 R ave. ≤ Rx max. ≤ 10.805 kg (106 kN)	Ø 315 R ave. ≤ Rx max. ≤ 14.679 kg (144 kN)	Ø 400 R ave. ≤ Rx max. ≤ 18.960 kg (186 kN)	Ø 400 R R ave. ≤ Rx max. ≤ 30.580 kg (300 kN)
--	--	--	--	--	--	--

TRAVELLING MASSES AT 2 SPEEDS, BASED ON THE COMBINATION OF COMPONENTS

NOMINAL SPEED (m/min)	TRAVELLING MASS (kg) ISO SERVICE GROUP (FEM)		"DGT" WHEEL GROUP Ø (mm)	"DGP" GEARED-MOTORS		SELF-BRAKING MOTOR SPECS		CODES FOR COMPONENTS				
	M4 (1Am)	M5 (2m)		REDUCER TYPE	MOTOR TYPE	POLES (N°)	POWER (kW)	"DGT" DRIVE WHEEL GROUP	"DGP" GEARED-MOTOR			
80/20	2.500	2.000	160	024	71K3L	2/8	0.40/0.09	DGT2A0M10	P0M2A43KA0			
	3.200	2.500			71K2L	2 with inv.	0.50		P0M2A41KA0			
	3.200	2.500			80K3C	2/8	0.50/0.12		P1M3A43AA0			
	4.000	3.200			80K3L	2/8	0.63/0.15		P1M3A43KA0			
	5.000	4.000			80K2L	2 with inv.	0.80		P1M3A41KA0			
	5.400	4.300			250	124	80K3L		2/8	0.63/0.15	DGT2A0M30	P1M3A23KA0
	6.900	5.500	80K2L	2 with inv.			0.80	P1M3A21KA0				
	10.800	8.600	100K3C	2/8			1.25/0.31	DGT4A0M12	P2M5A43AA0			
	13.500	10.800	100K3L	2/8			1.60/0.39		P2M5A43KA0			
	17.200	13.800	100K2L	2 with inv.			2.00	P2M5A41KA0				
	16.500	13.200	400	222			100K3L	2/8	1.60/0.39	DGT6A0M12 (rh) DGT6A0M22 (lh)		P2M5A23KA0
	20.600	16.500			100K2L	2 with inv.	2.00	P2M5A21KA0				
	25.800	20.600			334	112K3L	2/8	2.50/0.62	DGT6A0M32 (rh) DGT6A0M42 (lh)		P3M6B43KA0	
	33.000	26.400					112K2L	2 with inv.			3.20	P3M6B41KA0
	33.600	26.900			400 R	334	112K2L	2 with inv.	3.20		DGT6A0M82 (rh) DGT6A0M92 (lh)	P3M6B41KA0

The specifications refer to a single geared-motor; in case of two or more geared-motors, multiply the travelling mass by the number of geared-motors used. Verify that in relation to the rail's running surface width (b), average reaction (R ave) is compatible with the values listed in diagram pages 12, 13 and 14. The values for travelling mass in red require a verification of average reaction (R ave.) on each wheel, which must not exceed the following Rx. max. values:

Ø 125 R ave. ≤ Rx max. ≤ 3.670 kg (36 kN)	Ø 160 R ave. ≤ Rx max. ≤ 4.893 kg (48 kN)	Ø 200 R ave. ≤ Rx max. ≤ 7.340 kg (72 kN)	Ø 250 R ave. ≤ Rx max. ≤ 10.805 kg (106 kN)	Ø 315 R ave. ≤ Rx max. ≤ 14.679 kg (144 kN)	Ø 400 R ave. ≤ Rx max. ≤ 18.960 kg (186 kN)	Ø 400 R R ave. ≤ Rx max. ≤ 30.580 kg (300 kN)
--	--	--	--	--	--	--

SAMPLE GUIDELINES FOR SELECTING DRIVE UNITS FOR CRANES

To make the correct choice of drive unit, firstly establish all operating parameters which determine its operating limitations, defining and/or verifying the following factors (see sample guidelines for various "limit" cases listed below, purely by way of example):

1. Define operating data: nominal load, running speed (1 or 2 speed) and ISO service group (FEM);
2. Define: the mass (weight) of the crane or trolley in question and any accessories (frame, electrical system, etc.);
3. Define: in the case of a crane, the weight of the hoist/trolley or trolley/winch, or any movable masses (blocks, etc.) in the case of trolleys;
4. Calculate: the total mass to be traversed, i.e. the nominal load + all equipment masses (weight of crane, trolley, etc.);
5. Define: the no. of motor drive units, necessary for the running of the total mass to be travelled;
6. Calculate: the mass each drive wheel must travel (i.e. the ratio between the total mass and the no. of wheel drive groups);
7. Verify: the maximum, minimum and average reactions on the wheels, considering the load approach/eccentricities;
8. Verify: the congruency of the rail running surface width, in relation to the type of rail on which the wheels will run on.

1st Example: Single girder crane - Capacity 5 t - Span 16 m

1. nominal load P = 5000 kg; 2 crane running speeds = 40/10 m/min; ISO service group M4 (FEM 1Am)
2. weight of crane + accessories: M1 ≈ 2500 kg
3. weight of hoist + trolley: M2 = 500 kg
4. total mass to travel: 5000 + 2500 + 500 = 8000 kg
5. Motor drive units: no. 2
6. mass to travel for each motor drive wheel: 8000 / 2 = 4000 kg

Based on the selected speed and calculation of mass to be travelled for each drive wheel, derive the following components from the table on page 33:

NOMINAL SPEED (m/min)	TRAVELLING MASS (kg) IN SERVICE GROUP ISO M4 (FEM 1Am) IS IN kg	"DGT" WHEEL GROUP Ø (mm)	"DGP" GEARED-MOTOR		SELF-BRAKING MOTOR SPECS		CODES FOR COMPONENTS	
			GEARED-MOTOR TYPE	MOTOR TYPE	POLES (N°)	POWER (kW)	"DGT" DRIVE WHEEL GROUP	"DGP" GEARED-MOTOR
40/10	4.200 > di 4.000 to be traversed	125	022	71K3L	2/8	0.40/0.09	DGT1A0M10	P0M2A23KA0

At this point, verify the suitability of the Ø 125 wheel selected, in relation to its admissible reactions and type of rail:

7. reactions on the wheels, calculated as illustrated on page 12, for gauge "S" = 16,000 mm and supposing an approach "a" = 1000 mm:
 $R_{max} = 2.500/4 + [(500 + 5.000)/2] \cdot (1 - 1.000/16.000) \approx 3.203$ kg
 $R_{min} = 2.500/4 + 500/2 \cdot 1.000/16.000 \approx 641$ kg
 $R_{ave} = (2 \cdot R_{max} + R_{min})/3 = (2 \cdot 3.203 + 641)/3 \approx 2.349$ kg < 3.670 kg, corresponding to max. R admissible
8. supposing a flat laminated rail, with l = 40 and a running surface b = 38 (see table on page 11), from the diagram on page 12 we can deduce that, for a Ø 125 wheel with a **standard sheave** width, considering the factors (speed and rail running surface), the average admissible reaction for service group M4 (1Am) is:
 $R_{ave. admissible} \approx 2400$ kg > of the 2349 kg the wheel is subject to.

2nd Example: Double girder crane - Capacity 10 t - Span 20 m

1. nominal load P = 10,000 kg; 2 crane sliding speeds = 40/10 m/min; ISO service group M4 (FEM 1Am)
2. weight of crane + accessories: M1 ≈ 5,900 kg
3. weight of hoist + trolley: M2 ≈ 750 kg
4. total mass to travel: 10,000 + 5,900 + 750 = 16,650 kg
5. Motor drive units: no. 2
6. mass to travel for each motor drive wheel: 16,650 / 2 = 8325 kg

Based on the selected speed and calculation of mass to be traversed for each drive wheel, derive the following components from the table on page 33:

NOMINAL SPEED (m/min)	MASSA TRASLABILE (kg) GRUPPO DI SERVIZIO ISO M4 (FEM 1Am) È DI kg	"DGT" WHEEL GROUP Ø (mm)	"DGP" GEARED-MOTOR		SELF-BRAKING MOTOR SPECS		CODES FOR COMPONENTS	
			GEARED-MOTOR TYPE	MOTOR TYPE	POLES (N°)	POWER (kW)	"DGT" DRIVE WHEEL GROUP	"DGP" GEARED-MOTOR
40/10	9.400 > di 8.325 da traslare	200	134	80K3L	2/8	0.63/0.15	DGT3A0M10	P1M3B43KA0

At this point, verify the suitability of the Ø 200 wheel selected, in relation to its admissible reactions and type of rail:

7. reactions on the wheels, calculated as illustrated on page 12, for gauge "S" = 20000 mm and supposing a juxtaposition "a" = 1000 mm:
 $R_{max} = 5.900/4 + [(750 + 10.000)/2] \cdot (1 - 1.000/20.000) \approx 6.581$ kg
 $R_{min} = 5.900/4 + 750/2 \cdot 1.000/20.000 \approx 1.494$ kg
 $R_{ave} = (2 \cdot R_{max} + R_{min})/3 = (2 \cdot 6.581 + 1.494)/3 \approx 4.885$ kg < 7.340 kg, corresponding to the admissible R max.
8. supposing a flat laminated rail, with l = 50 and operating band b = 48 (see table on page 11), from the diagram on page 13 we can deduce that, for a Ø 200 wheel with a **standard sheave** width, considering the factors (speed and operating bandwidth), the average admissible reaction for the service group M4 (1Am) is:
 $R_{ave. admissible} \approx 5.500$ kg > of the 4.885 kg the wheel is subject to.

3rd Example: Trolley for winch - Capacity 40 t – Gauge 2.4 m

1. nominal load P = 40.000 kg; 2 trolley running speeds = 20/5 m/min; ISO service group M5 (FEM 2m)
2. weight of crane + accessories: M1 ≈ 2.600 kg
3. weight of block + ropes: M2 ≈ 400 kg
4. total mass to travel: 40.000 + 2.600 + 400 = 43.000 kg
5. motor drive units: n° 2
6. mass to travel for each drive wheel: 43.000 / 2 = 21.500 kg

Based on the selected speed and calculation of mass to be travelled for each drive wheel, derive the following components from the table on page 32:

NOMINAL SPEED (m/min)	TRAVELLING MASS (kg) IN SERVICE GROUP ISO M5 (FEM 2m) IS IN kg	"DGT" WHEEL GROUP Ø (mm)	"DGP" GEARED-MOTOR		SELF-BRAKING MOTOR SPECS		CODES FOR COMPONENTS	
			GEARED-MOTOR TYPE	MOTOR TYPE	POLES (N°)	POWER (kW)	"DGT" DRIVE WHEEL GROUP	"DGP" GEARED-MOTOR
20/5	21.600 > di 21.500 to be traversed	250	232	80K2L	2 con inverter	0.80	DGT4A0M32	P2M3B21KA0

At this point, verify the suitability of the Ø 250 wheel selected, in relation to its admissible reactions and type of rail:

7. reactions on the wheels, calculated as illustrated on page 12, for gauge "S" = 2.400 mm and supposing the centred hook "a" = 1.200 mm:
 $R_{max} = 2.600/4 + [(400 + 40.000)/2] \cdot (1 - 1.200/2.400) \approx 10.750$ kg
 $R_{min} = 2.600/4 + 400/2 \cdot 1.200/2.400 \approx 750$ kg
 $R_{ave} = (2 \cdot R_{max} + R_{min})/3 = (2 \cdot 10.750 + 750)/3 \approx 7.417$ kg < 10.805 kg, corresponding to max. R admissible
8. supposing a flat laminated rail, with l = 60 and operating band b = 58 (see table on page 11), from the diagram on page 13 we can deduce that, for a Ø 250 wheel with a **standard sheave** width, considering the factors (speed and rail running surface), the average admissible reaction for the service group M5 (2m) is:
 $R_{ave. admissible} \approx 8.300$ kg > of the 7.417 the wheel is subject to.

4th Example: Gantry crane - Capacity 40 t - Span 27 m

1. nominal load P = 40.000 kg; 2 crane running speeds = 32/8 m/min; service group ISO M5 (FEM 2m)
2. weight of crane + accessories: M1 ≈ 27.000 kg
3. Weight of trolley + hoist: M2 ≈ 3.000 kg
4. total mass to travel: 40.000 + 27.000 + 3.000 = 70.000 kg
5. motor drive units: no. 2
6. mass to travel for each drive wheel: 70.000 / 2 = 35.000 kg

Based on the selected speed and calculation of mass to be travelled for each drive wheel, derive the following components from the table on page 33:

NOMINAL SPEED (m/min)	TRAVELLING MASS (kg) IN SERVICE GROUP ISO M5 (FEM 2m) IS IN kg	"DGT" WHEEL GROUP Ø (mm)	"DGP" GEARED-MOTOR		SELF-BRAKING MOTOR SPECS		CODES FOR COMPONENTS	
			GEARED-MOTOR TYPE	MOTOR TYPE	POLES (N°)	POWER (kW)	"DGT" DRIVE WHEEL GROUP	"DGP" GEARED-MOTOR
32/8	41.300 > 35.000 to be traslated	400 R	232	100K2L	2 con inverter	2.00	DGT6A0M62 (rh) DGT6A0M72 (lh)	P2M5B21KA0

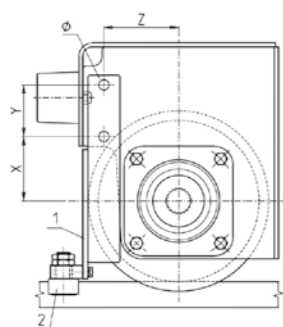
At this point, verify the suitability of the Ø 400 wheel selected, in relation to its admissible reactions and type of rail:

7. reactions on the wheels, calculated as illustrated on page 12, for span "S" = 27.000 mm and supposing a position "a" = 1.500 mm:
 $R_{max} = 27.000/4 + [(3.000 + 40.000)/2] \cdot (1 - 1.500/27.000) \approx 27.056$ kg
 $R_{min} = 27.000/4 + 3.000/2 \cdot 1.500/27.000 \approx 6.834$ kg
 $R_{ave} = (2 \cdot R_{max} + R_{min})/3 = (2 \cdot 27.056 + 6.834)/3 \approx 20.315$ kg < 30.580 kg, corresponding to max R admissible
8. supposing a flat laminated rail, with l = 100 and operating band b = 98 (see table on page 11), from the diagram on page 14 we can deduce that, for a Ø 400 R with **special sheave** width, considering the factors (speed and rail running surface), the average admissible reaction for the service group M5 (2m), is:
 $R_{ave. admissible} \approx 20.550$ kg > of the 20.315 kg the wheel is subject to.

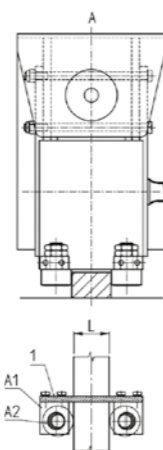
ACCESSORY COMPONENT OF THE BRIDGE CRANE END-CARRIAGES

GUIDE ROLLS

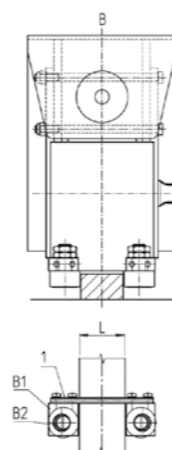
- 1: Load-bearing frame
- 2: Idle pin bearing



- Layout A:
- A1: Idle pin bearing support
- A2: Idle pin eccentric



- Layout B:
- B1: Idle pin bearing support
- B2: Idle pin eccentric



DGT	CODE	WHEEL BOX PERFORATION (mm)				TRACK WIDTH L (mm)			
		X	Y	Z	Ø	LAYOUT A		LAYOUT B	
						MIN	MAX	MIN	MAX
1	DGT1A0F10	52	50	63	9	35	45	50	60
2	DGT2A0F10	70	50	77	11	40	50	55	65
3	DGT3A0F10	85	60	96	13	45	55	60	70
4	DGT4A0F10	100	80	116	13	55	65	70	80
5	DGT5A0F10	122,5	75	141	17	60	70	75	85
6	DGT6A0F10	152	80	178	21	70	80	85	95

DONATI WEBSITE



Donati's window on the world for customer service.

Manuals and product information

The new Donati website has been designed to assist customers so they can easily find all of the updated information on Donati products at any time. The Donati website makes it simple to consult and download product catalogues, technical manuals and product information sheets.

Donati Shop

The Donati Shop makes it possible to quickly and independently handle spare parts requests, thus reducing waiting times for customers.

Contact Section

The new contact section divided by departments lets you address your requests to the right team, so our staff can provide a faster and more accurate answer.

LEONARDO CONFIGURATION SYSTEM



Leonardo Configuration System is the Donati configurator system that lets you configure and generate offers for Chain hoists, Jib cranes and Crane sets, easily and quickly; it lets you rapidly and efficiently respond to your customers' requests.

The suite is composed of two configurators:

Leonardo Product Configurator:

Used to configure chain hoists and jib cranes alone or in combination

Leonardo Crane Set Configurator:

Used to configure bridge cranes complete with all necessary accessories and Donati hoists.



visit donaticranes.com
and keep up to date

Donati Sollevamenti S.r.l.

Via S. Quasimodo, 17
20025 Legnano (MI) - Italy
Tel +39 0331 14811
Fax +39 0331 1481880

dvo.info@donaticranes.com
www.donaticranes.com